

Presentation of <u>Vehicle Energy consumption</u> <u>Calculation TO</u>ol (VECTO)

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Simulation tool to calculate both, fuel consumption and CO₂ emissions from the **whole** vehicle



Vecto development

- VECTO has been developed by the Commission (DG CLIMA and JRC) with TUG support over the last two years
- ACEA, OEMs and component manufacturers have been also involved and provided key input and test vehicles
- DG CLIMA is the leader for this project
- Further development will take place in the next years (contract already launched).



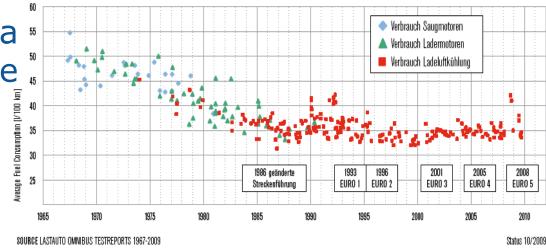


Why do we want to measure HDVs

No official/unified measurement or certification scheme for HDVs in EU (unlike for cars and vans)

Average Fuel Consumption (Gross Vehicle Weight 38/40 t)

Some single data exist but indicative in nature





HDVs are more complicated than LDVs

- Low, medium, high, long, short cab etc
- 2,3,4,5,6 axles, 4x2, 4x4, 6x2, 6x4, 6x6 etc
- Different tires for each axle, single/twin tires etc
- Same engine but different gear boxes/axles ect
- Rigid, semi-trailer, tractor, coach, bus, citybus etc
- Any combination mentioned above

Millions of types!!!



HDV CO₂ in the EU Policy context HDVs account for

- About 6% of total EU GHG emissions
- About 25% of total GHG road transport emissions
- Freight transport (trucks) main source of HDV emissions
- Passenger transport: buses and coaches

Roadmap for low carbon economy in 2050 :

- Reduce GHG emissions from 80% to 95% by 2050 (Base 1990)
- Transport sector foreseen to reduce emissions between 54 and 67% by 2050

White Paper on Transport:

- Target 60% reduction in GHG emissions by 2050 (Base 1990)
- 20% by 2030 (Base 2008)



Regulatory situation in EU

Existing Regulations setting performance standards for:

- Cars (Reg. 443/2009), and
- Vans (Reg. 510/2011)

Currently no legislation setting performance standards for HDV CO₂ emissions or parts thereof

Current test cycle procedure for HDVs is based on the engine (e.g. for regulation air pollutant emissions), not the whole vehicle







• Serve for all possible **policy steps** including:

- Monitoring, reporting **and certification**
- Improve market forces (e.g. by comparable customer information)
- Labelling
- Improve/help foot-printing schemes
- Give a reliable **real world** picture of the fuel consumption/CO₂ emissions accuracy ~ 95 %
- Fit for the **future** (include new technologies)
- Minimize burden on OEMs



History

So far examined and result:

Approaches explored:

- Measurement on a chassis dynamometer
- Measurement with PEMS
- Component measurement and model simulation

Selected option:

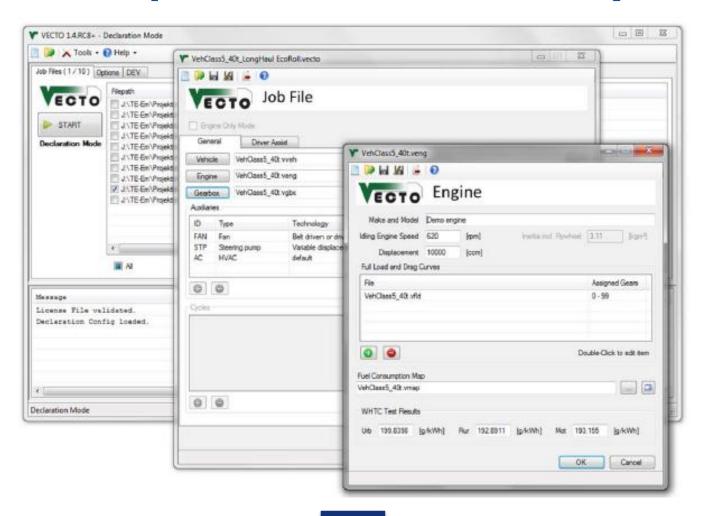
Component measurement and model simulation for the **whole vehicle (truck and trailer)**

Methodology ("VECTO") considers:

Engine, driving resistances of whole vehicle (rolling, aerodynamic), gearbox, most relevant auxiliaries



VECTO Graphical User Interface (GUI)





VECTO's modes

VECTO offers a <u>declaration mode</u>, where all generic data and the test cycle are allocated automatically as soon as the **vehicle class** is defined.

An <u>engineering mode</u> is also offered, where the user can select and change all input data to allow recalculation of test data e.g. for model validation.



VECTO output

In the **declaration mode** of VECTO fuel consumption and CO₂ emissions are automatically calculated for all CO₂ test cycles allocated to the vehicle for average payload, full load and empty driving. Results are given in **g/km** and **g/ton-km** or **g/pass-km**.

Which of these values will be used in a final certification process is not decided yet.



Components and input data

For the following components, relevant **input data** for VECTO have to be delivered from standardised test procedures :

- -- Vehicle mass
- -- Tires (dimensions and rolling resistance coef)
- -- Engine (engine fuel flow map)

-- Transmission (transmission ratios, loss maps for gear box and axle, default values optional)

-- Aerodynamic drag (Cd x A, for some vehicle classes generic values can be used)



Components and generic values

For the following components **generic values** are defined, which are allocated by the software VECTO to the vehicle depending on the vehicle class and mission profile. :

- Auxiliaries (alternator, air compressor, alternator, steering pump, cooling fan, Heating Ventilation AC-HVAC)
- Mass of the standard bodies and trailers
- Vehicle payload (truck) or passengers weight (bus)
- Test cycle



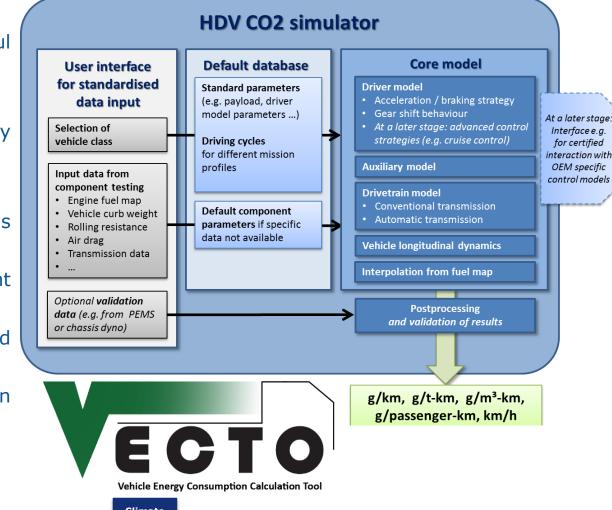
VECTO: Programme structure

Developed initially to cover:

- Delivery trucks (long haul and regional-city)
- Coaches
- Effort to include city buses

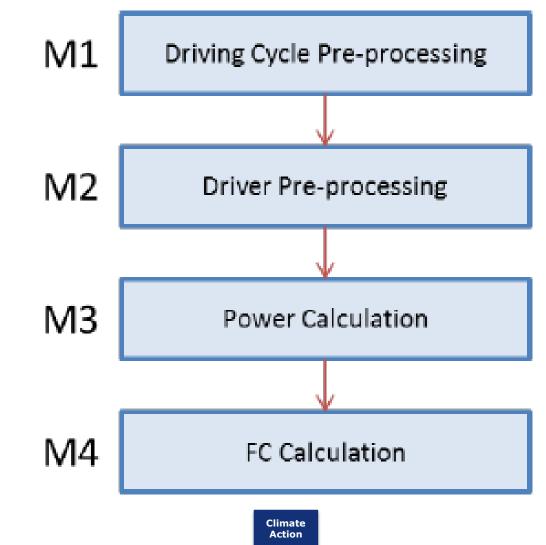
Effort to standardize:

- Measurement protocols for input data generation
- Individual component simulation models
- Mission profiles and cycles
- Evaluation / validation approaches



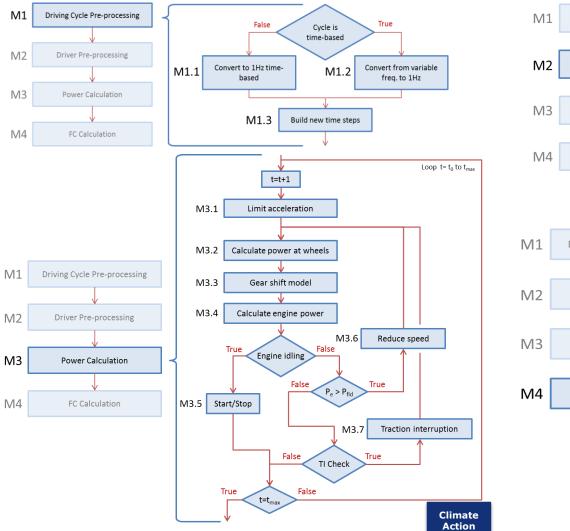


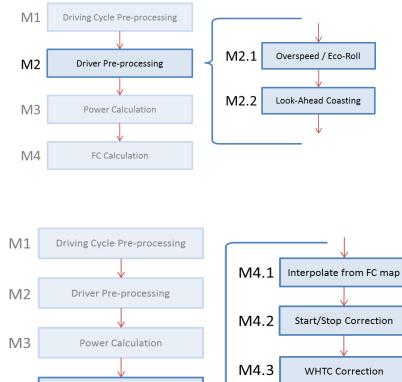
Model structure - Four main modules





Model structure - Four main modules





FC Calculation



Tasks of single modules (1)

In **Driving Cycle Pre-processing (M1)** the distance-based driving cycle (mission profile) is being converted to 1Hz. Time-based cycles are converted to 1Hz if necessary.

Driver Pre-processing (M2) applies driver functions to the driving cycle which can't be considered later in the backwards power calculation (M3) like Over-speed or Look-Ahead Coasting.



Tasks of single modules (2)

Power Calculation (M3) is the core of the model. Here the engine operation points (engine torque and speed) are calculated for each time step considering driving resistances and powertrain losses and auxiliary power demands.

Finally in **FC Calculation (M4)** the fuel consumption (FC) is being interpolated from the stationary FC map and the WHTC correction is applied.



Mission profiles

Trucks

- Urban delivery
- Regional delivery
 - Long haul
 - Construction
 - Municipal utility

Buses and coaches

- City-bus heavy urban
 - City-bus urban
 - City-bus suburban
 - Interurban bus
 - Coach



Climate Action

Rigid and tractors classification

The generic values are allocated to the vehicle by VECTO automatically depending on the HDV class in which the vehicle falls.

Classification, mission profile or type of use and identification of standard bodies for each type of HDV

| | | | | | | Segmentation | | | | | orm body | | |
|---|---------------------------------|-----------------------|-----------------|--------------|--|--------------|-------------------|----------------|-------------------|--------------|---------------|------------------|----------------------|
| <u> </u> | Identification of vehicle class | | | | (vehicle configuration and cycle allocation) | | | allocation | | | | | |
| Axles | Axle configuration | Chassis configuration | Maximum GVW [t] | < Vehiœ dass | | Long haul | Regional delivery | Urban delivery | Municipal utility | Construction | Standard body | Standard trailer | Standard semitrailer |
| 2 | 4x2 | Rigid | >3.5 - 7.5 | 0 | | | R | R | | | BO | | |
| | | Rigid or Tractor | 7.5 - 10 | 1 | | | R | R | | | B1 | | |
| | | Rigid or Tractor | >10 - 12 | 2 | | R | R | R | | | B2 | | |
| | 4x2 | Rigid or Tractor | >12 - 16 | 3 | | | R | R | | | B3 | | |
| 2 | | Rigid | >16 | 4 | | R+T | R | | R | | B4 | T1 | |
| 2 | | Tractor | >16 | 5 | | T+S | T+S | | | | | | S1 |
| | | Rigid | 7.5 - 16 | 6 | | | | | R | R | B1 | | |
| | 4x4 | Rigid | >16 | 7 | | | | | | R | B5 | | |
| | | Tractor | >16 | 8 | | | | | | T+S | | | W1? |
| | 6x2/2-4 | Rigid | all weights | 9 | | R+T | R | | R | | B6 | T2 | |
| | | Tractor | all weights | 10 | | T+S | T+S | | | | | | S2 |
| 3 | 6x4 | Rigid | all weights | 11 | | | | | | R | B7 | | |
| | | Tractor | all weights | 12 | | | | | | R | | | S3 |
| | 6x6 | Rigid | all weights | 13 | | | | | | R | W7 | | |
| | | Tractor | all weights | 14 | | | | | | R | W7 | | |
| | 8x2 | Rigid | all weights | 15 | | | | | | R | B8 | | |
| 4 | 8x4 | Rigid | all weights | 16 | | | | | | R | B9 | | |
| | 8x6 & 8x8 | Rigid | all weights | 17 | | | | | | R | W9 | | |
| R = Rigid & Body R+T = Rigid & Body & Trailer *) T+S = Tractor & Semitrailer W =no (Cd*A) measurement, only vehicle weight and frontal are *) Whether it is sufficient to simulate the truck-trailer combination based on cd*A for Rigid & Body or the full-vehicle test for aerodynamic drag has to be performed additionally with Rigid & Body & Trailer has to be clarified | | | | | | | | | n namic | | | | |



Busses classification

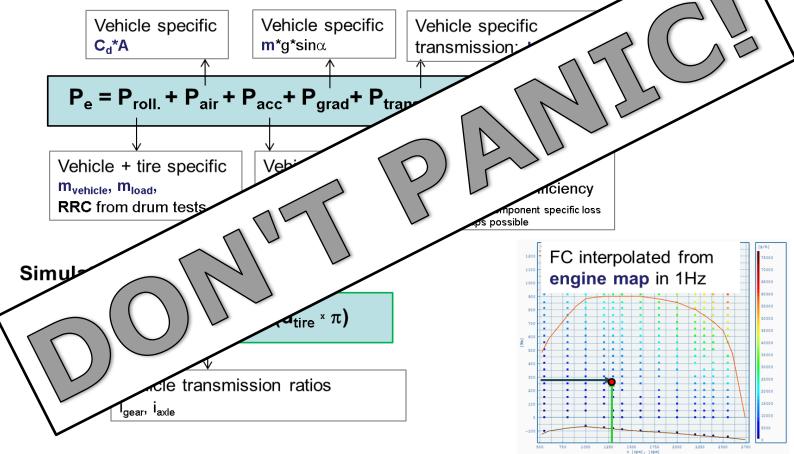
| | | | Identification of vehicle class | Π | Segmentation and cycle allocation | | | | ation | | |
|-------|-----------------------|--------------------------|--|--------------------|-----------------------------------|---|-------------|-------|----------|------------|-------|
| Axles | Axle configuration | Chassis configuration | Characteristics | Maximum GVW [t] | < Vehice class | | Heavy Urban | Urban | Suburban | Interurban | Coach |
| | | City | Class I + low floor or low entry, no luggage compartment | <18 | B1 | | HU | UR | SU | | |
| 2 | 4x2 | Interurban | Class II + luggage compartment and/or floor height <0.9m | <18 | B2 | | | | | IU | |
| | | Coach | Class III + floor height > 0.9m and/or double decker | <18 | B3 | | | | | | CO |
| | | City | Class I + Low floor or low entry, no luggage compartment | >18 | B4 | Π | R | UR | SU | | |
| 3 | 6x2 | Interurban | luggage compartment and/or floor height < 0.9m | >18 | B5 | | | | | IU | |
| | | Coach | floor height <u>></u> 0.9m and/or double decker | >18 | B6 | | | | | | CO |

For each class the corresponding test cycles, the standard body or trailer and the payload are defined as well as the data relevant for the simulation of the generic auxiliaries.



Simulation of engine power

Simulation of engine power:

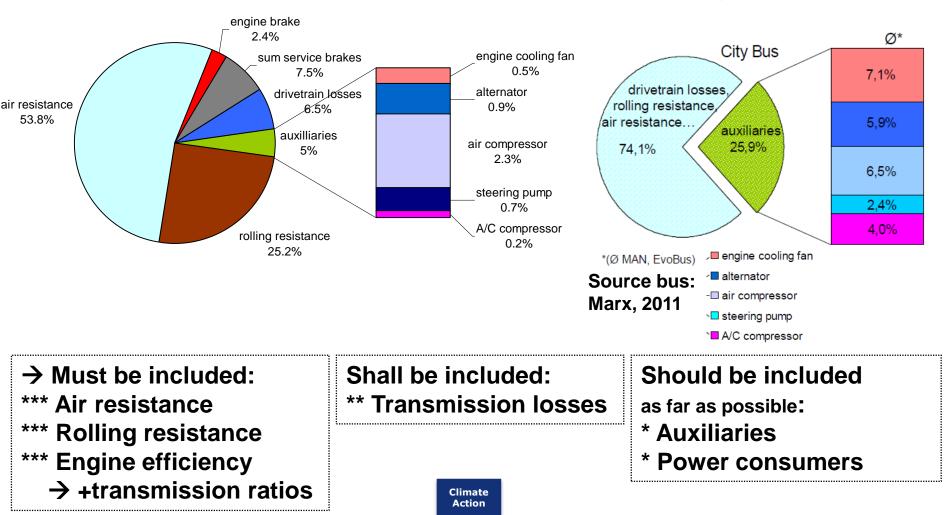




Shares of energy consumption

EURO V semitrailer 28 t

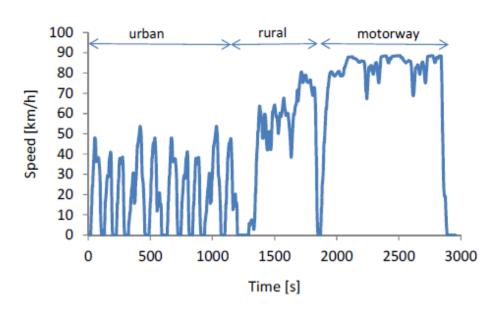
EURO V city bus





Evaluation of simulation program

- Selected 12 ton truck, measured over various conditions on chassis dyno
- Performed simulations with VECTO
- Verify good correlation between measured and simulated values
- Compared against 3 commercially available simulators
- First sensitivity analysis uncertainties quantification

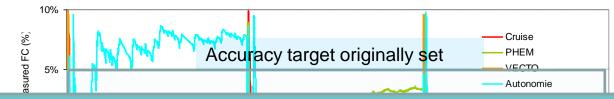


| Vehicle Empty Mass [kg] | 8862 |
|--|---|
| Rated power [kW] | 185 |
| Rated Torque [Nm] | 840 |
| Displacement [cm] | 6000 |
| Idling speed [rpm] | 600 |
| A_cross x Cd [m2] | 6.16 (derived from track measurements) |
| Tyre RRC [-] | 0.0077 (derived from track measurements) |
| Fuel Consumption Map | From steady state RPM vs Torque points as measured by manufacturer |
| Gearbox & Final Drive characteristics | Ratios and efficiencies as provided by manufacturer |
| Auxiliary power consumption | power functions as provided by manufacturer |
| Auxiliary operation | As measured during tests |



Fuel consumption over sub-cycle (normalized by measured average 100=measurement)

| | VECTO | Cruise | PHEM | Autonomie |
|---------------|-------|--------|------|-----------|
| Urban part | 99 | 96 | 101 | - |
| Rural part | 98 | 101 | 96 | 98 |
| Motorway part | 98 | 101 | 98 | 96 |



96-98% accuracy with simulation tools





Proof of concept activity

Scope:

- Prove that simulation based monitoring can deliver results that accurately reflect fuel consumption and performance of modern HDVs
- Verify the validity and soundness of the approach
- Extensive measurements concluded February 2013
- Joint Commission-ACEA activity Included
 - 2 HDVs provided by DAF and Daimler
 - Proving ground testing (Iveco's circuit)
 - Chassis dyno testing (JRC)
 - On road / PEMS testing (JRC)
 - Engine test bed testing (JRC)





Vehicles used

| ОЕМ | Daimler | DAF |
|-----------------------------|---------|--------|
| Model | Actros | CF75 |
| Maximum vehicle weight [kg] | 40000 | 18600 |
| Test mass [kg] | 33580 | 14270 |
| Engine Emission Standard | Euro VI | Euro V |
| Rated power [kW] | 330 | 265 |
| Rated Torque [Nm] | 220 | 1050 |
| Displacement [I] | 12.8 | 9.2 |
| | | |

Climate Action

Fuel Consumption Map

From steady state RPM vs Torque points as measured by manufacturers

Gearbox & Final Drive characteristics



As provided by manufacturers







JRC SCIENTIFIC AND POLICY REPORTS

Development of a CO₂ certification and monitoring methodology for Heavy Duty Vehicles – Proof of Concept report

Georgios Fontaras

Contributing authors: Martin Rexeis, Stefan Hausberger, Antonius Kies (TUG) Jan Hammer, Leif-Erik Schulte (TÜV), Konstantinos Anagnostopoulos, Urbano Manfredi, Massimo Carriero and Panagiota Dilara (JRC)

2014

The full report can be found on DG Clima's website

http://ec.europa.eu/clima/policies/transpo rt/vehicles/heavy/docs/hdv_co2_certificati on_en.pdf

Climate

Action

Report EUR 26452 EN



Report conclusions and follow up

- Simulated fuel consumption was calculated with a range of $\pm 3\%$ from the real world measurements or even less.

- Finalize and validate topics remaining open in the methodology such as gearbox and driveline efficiency, auxiliary units power consumption, automatic gear shifting strategies, mobile air-conditioning simulation for city buses.

- Perform a sensitivity analysis in order to more accurately quantify the uncertainty of the method for different vehicle types/categories.

- Investigate the necessary conditions for expanding the methodology to other HDV categories.



- VECTO development: on-going
- Dissemination and trials: from 2013 to mid-2016
- Possible legislative proposals: 2015
- Possible first reporting year: 2018





Thank you for your attention

- VECTO demonstration will follow
- I will be happy to address your questions
- More info can be found at: <u>http://ec.europa.eu/clima/policies/transport/vehicles/he</u> <u>avy</u>
- Contact details:

Dimitrios SAVVIDIS: <u>dimitrios.savvidis@ec.europa.eu</u>